# MICHIGAN STATE UNIVERSITY Project Plan Classifying Target Vehicles for Adaptive Cruise Control The Capstone Experience

#### Team Bosch

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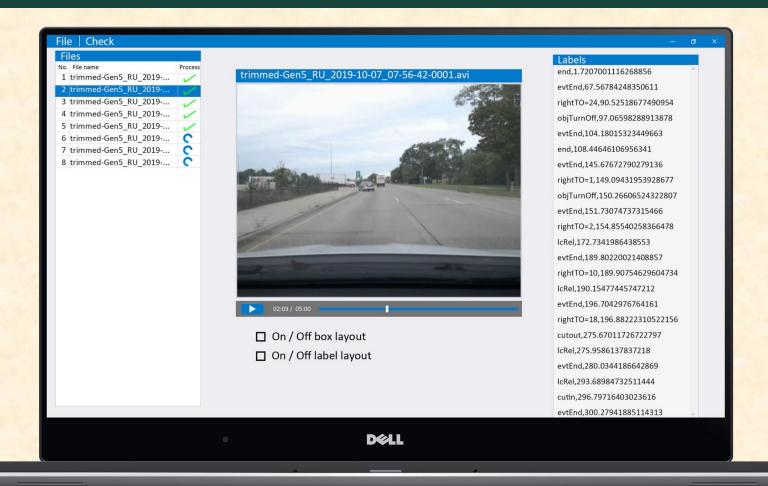
#### **Functional Specifications**

- Currently Bosch employs people to manually label video data. This is a tedious and time-consuming process.
- Our goal is to develop a tool which automatically creates labels using machine learning.
- Process recorded video data to perform vehicle and lane recognition
- Automatically label target objects
  - "Target Object Present"
  - "Host Vehicle Changing Lanes"
  - "Target Object Cutting into Host Lane"
- Output a label file with 80% 90% labeling accuracy

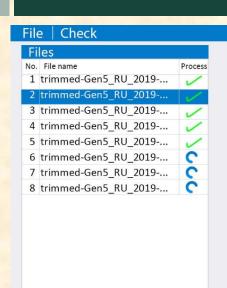
#### **Design Specifications**

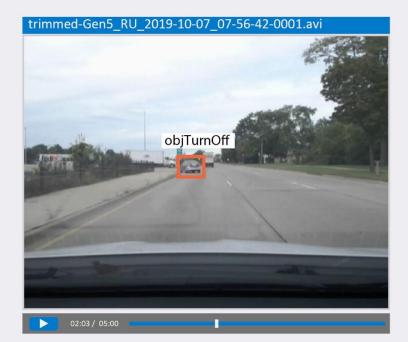
- Desktop program
- Display box and Label Overlay on Video
- Display predicted Label Confidence Rating
- Creates a text file with labels and event timestamps
- Use Case: Save manual labor on dataset labeling

### Screen Mockup: Main Screen



#### Screen Mockup: Overlays

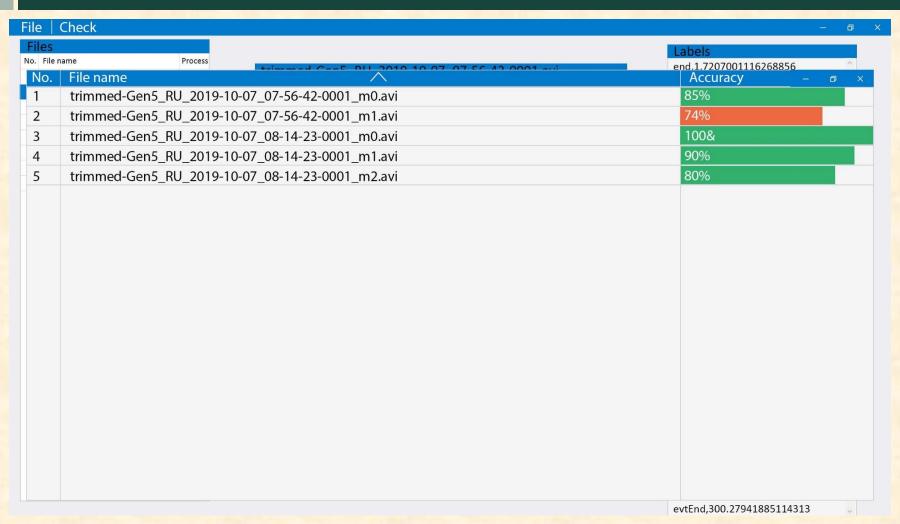




- On / Off box layout
- On / Off label layout

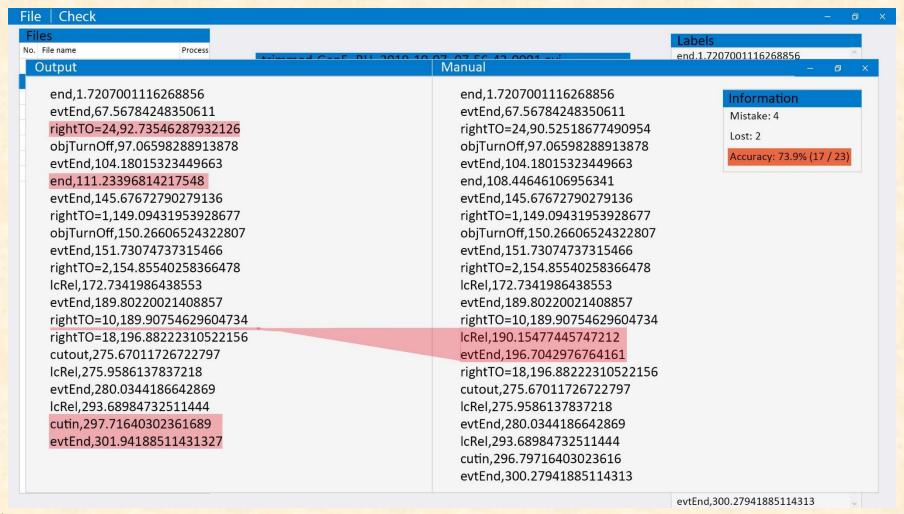


# Screen Mockup: Confidence Rating





## Screen Mockup: Comparison View





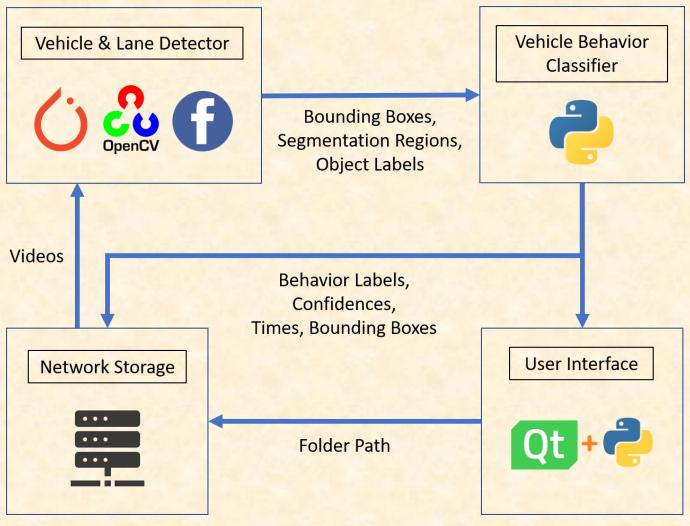
The Capstone Experience

#### **Technical Specifications**

- The program takes an AVI video file as input and processes it with a machine learning model
- Facebook's Detectron2 for vehicle detection and semantic segmentation
- Canny edge detection for lane line detection
- Outputs a text file with label predictions and timestamps to events of interest
- Ray for concurrent processing of videos off of the python GUI thread



# System Architecture





#### System Components

- Hardware Platforms
  - External Hard Drive containing video data
- Software Platforms / Technologies
  - Python
  - PyQT
  - OpenCV
  - Facebook's Detectron2
  - PyTorch
  - Ray



#### Risks

- Large Data
  - Managing the large amount of compressed data
  - Programmatically access compressed videos using a Python library
- Model Accuracy
  - Fine-tuning the feature extraction model
  - Consider cloud computing environment such as Google Cloud **Platform**
- Bad Data
  - Low quality data points in the dataset
  - Locate and remove those data points
- Algorithm Integration
  - Label generation and computer vision algorithms
  - Research box / line collision test and common computer vision algorithms

