**MICHIGAN STATE** UNIVERSITY **Beta Presentation Robotic Job Coaching The Capstone Experience** Team Michigan State University CSE Adam Cohen **Kaiwen Jiang** Olivia Pal Stavro Polis **Kyle Roleson Ekene Umobi** Department of Computer Science and Engineering **Michigan State University** 

Fall 2024



From Students... ...to Professionals

#### **Project Overview: Problem**

- In-person job coaching is inefficient
  - One coach can only manage so many clients
  - May be significant time delay in receiving assistance
  - Limits how much attention each client can receive
- Existing virtual job coaching also has issues
  - The coach has a static view of the work area
  - The coach can't gain a proper understanding of their surroundings or the work

#### **Project Overview: Solution**

- Streamline connecting job coaches and clients with an iOS application
  - Job coach can assist many people simultaneously
  - Improved availability to assist clients
- Allow coach to remotely control their view using a robotic arm
  - No longer reliant on the client to manage the camera
  - Can freely and intuitively observe the work area without interruption
- Improved experience for both parties, especially for clients with cognitive disabilities

### System Architecture



#### **Create Session Screen**



## Set Profile Picture

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## Select Coach Screen

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<b>(</b>	Kenny		•

#### **Enter Reason For Help**

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## Waiting Room



## **Conference Screen (Coach)**



#### View Client's Reason



#### **Conference Screen (Client)**



## **Reverse Call Option**



#### **Accept Reverse Call**

8-29 PM Wed Nov 13	Select Coa	ach	♥ @ 97% ■
€ġ	Any Coacl	h	
	Kenny	Accept Coach Call? No Yes	

### Kinova Jaco 2 Simulator



## Admin Home Page

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#### **Create User Page**

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	Allowed Users
	Coach
	Denied Users
	Kenny Coach John
	Update
	Team Michigan State University CSE
The Capstone Experience	am Michigan State University CSE Beta Presentation 1

## Call Logs Page



The Capstone Experience

#### What's left to do?

- Stretch Goals
  - TURN server
  - Recording calls
  - Have way for a client to re-convey urgency
  - Laser indicator
- Other Tasks
  - Fix edge-cases relating to event de-sync on visualization
  - If we get a robot, implement with it

#### **Questions?**

